

特別講演のご案内

講演タイトル : Learning with Function Approximators
http://www.cs.berkeley.edu/~eiji/TMP/talk_at_TMU_June04.txt

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日時 : 2004年6月21日 (月) ~ 23日 (水) , 4:20 - 5:50

場所 : 6月21日 (月) 大学院講義室 (27-470)
6月22日 (火) 大学院演習室 (27-469)
6月23日 (水) 大学院講義室 (27-470)

参加費 : 無料

(講演は, 日本語です)

講演内容 :

6月21日 (月)

On derivation of MLP-backpropagation from the Kelley-Bryson optimal-control gradient formula

6月22日 (火)

Introduction to neuro-dynamic programming and reinforcement learning

6月23日 (水)

Second-order optimal control methods for learning with function approximators

講演概要 :

In the three-day series of tutorial lectures, I describe "learning with function approximators" in the context of neural-network (NN) supervised learning and reinforcement learning (also known as neuro-dynamic programming). I begin with fundamental concepts of classical dynamic programming (DP), and then derive the well-known backpropagation [for multilayer-perceptron (MLP) learning] from the so-called Kelley-Bryson optimal-control gradient formula. Here, I shall demonstrate the use of a non-optimal value function in the spirit of DP. In optimal-control theory, it also plays an important role in developing a class of second-order methods that start with a given nominal non-optimal state trajectory; in particular, I spotlight stagewise Newton and differential dynamic programming (DDP). Such second-order optimal-control methods can be employed for accelerating supervised NN-learning as well as reinforcement learning with function approximators. For optimization purpose, I emphasize that it is very important to pursue a good compromise between the steepest-descent method and a Newton-type method. Besides the theoretical aspects of the posed methods, I shall illustrate in detail small-scale longest path problems in non-Markovian settings to give a clear idea on reinforcement learning approaches as well as a classical DP algorithm. This series of talks is largely based on joint work with Stuart Dreyfus, UC Berkeley.

連絡先 :

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